Serial No. 09/680,089 Examiner Alavi Filing Date: October 5, 2000

REMARKS

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As a first matter, the Applicants thank the Examiner for allowing claims 1-10 and 13. Applicants have amended the spelling of the word color in these claims as requested by the Examiner. Claims 11 and 12 have been rewritten and claims 14-19 added to address the multiple dependencies in the original application. All amendments and additions to the claims are made as to form and do not change or modify the scope of the claims as originally filed.

Pursuant to the draftsman's objections, the drawings are being resubmitted in black and white. If necessary, formal black and white drawing will be prepared and submitted.

The Abstract has been modified to shorten it and have it read more narratively as suggested by the Examiner. Both a marked up version of the Abstract and a substitute (clean) version of the Abstract are submitted herewith.

Please amend the title of the application as suggested by the Examiner.

The Applicants are submitting both a marked up version of the specification and a new substitute (clean) specification, as requested. The specification has only been modified to show the change in the title as suggested by the Examiner, and to show the change in the spelling of the work color, also as requested by the Examiner. No substantive changes have been made to the specification.

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CONCLUSION

Based on at least the application, and the remarks herein, Applicants request withdrawal of the remaining objections and believe the present application to be in condition for allowance, which action is respectfully requested.

Respectfully submitted,

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METHODS <u>FOR_APPLYING COLOURCOLOR</u> MEASUREMENT BY MEANS | 5 OF AN ELECTRONIC IMAGING DEVICE

The invention pertains to methods applying eolourcolor measurement by means of an electronic imaging device. More particularly, the invention pertains to a method of determining a eolourcolor formula for matching a selected eolourcolor measured with an electronic imaging device. The invention is also directed to a method of determining a eolourcolor formula for matching a selected eolourcolor of a textured material measured with an electronic imaging device. Finally, the invention is directed to a method for checking a selected eolourcolor measured with an electronic imaging device with a standard eolourcolor sample.

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It is well-known to measure selected <u>colourcolors</u> with the aid of <u>colourcolor</u> meters, such as spectrophotometers and tri-stimulus meters. The measured signals may be used for the determination of a <u>colourcolor</u> formula. Thus U.S. 4,813,000 discloses measuring a selected <u>colourcolor</u> with the aid of a tri-stimulus <u>colourcolor</u> analyser and using the measured chromaticity data to search for a <u>colourcolor</u> formula in a databank. A series of articles by W. R. Cramer published in *Fahrzeug + Karosserie*, 9, 1997, 11-12, 1997, and 1-5, 1998, describes commercial applications of measuring a selected <u>colourcolor</u> with the aid of a spectrophotometer and using the measured spectral data to search for a <u>colourcolor</u> formula in a databank. Such methods are especially suitable for use at points of sale where paints have to be available in every <u>colourcolor</u>.

30 It is also possible to use the measured signals to check the selected colourcolor with a standard colourcolor sample. Such a method is currently used in the printing inks industry.

The human eye is highly sensitive to eeleurcolor differences. If a eeleurcolor is to be matched, it is essential that the measurement of the eeleurcolor be as accurate as possible. High measuring accuracy requires calibration. To this end there are fixed standards defining eeleurcolor in terms of standard values, so-called colorimetric data. Most common colorimetric data has been laid down by the Commision International de l'Eclairage (CIE), e.g., CIELab (L*_{ab}, a*, b*), CIEXYZ (X, Y, Z), and CIELUV (L*_{uv}, u*, v*). Spectral measuring data and tristimulus measuring data therefore have to be converted to colorimetric data if a spectrophotometer or a tri-stimulus meter is to be calibrated.

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The drawback to spectrophotometers is that they are very delicate instruments. Hence a certain expertise is required on the part of the user which is not always available at the aforementioned points of sale. Moreover, spectrophotometers are expensive. A further drawback to spectrophotometers and tri-stimulus meters is that they cannot be used for measuring colourcolor appearance including texture of the material.

The invention pertains to a method of determining a colour<u>color</u> formula for matching a selected colour<u>color</u> measured with an electronic imaging device, which method comprises the following steps:

- a) an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colour signals of at least two calibration colour specifical two calibration colour specifical specif
- at the same time or in a next step the selected colourcolor is measured with the aid of the electronic imaging device;
 - using a mathematical model, parameters are calculated for converting the measured eolour<u>color</u> signals of the calibration eolour<u>color</u>s to the known colorimetric data;

- d) using the mathematical model and the calculated parameters, the eeleurcolor signals of the measured selected eeleurcolor are converted to colorimetric data; and
- e) using a databank, the colourcolor formula is determined of which the colorimetric data most closely matches the calculated colorimetric data of the measured selected colourcolor.

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The invention has the advantage that it is possible to make use of inexpensive consumer electronics. Consumer electronics often do not have the accurate settings required for specialist applications. The method according to the invention now makes it possible to utilise an inaccurate device for the determination of a colourcolor formula for matching a selected colourcolor and yet achieve a high level of measuring accuracy. In addition, the method can be performed easily by a non-specialist without him needing extensive training. The method according to the invention also makes it possible to measure a specific attribute of the colourcolor appearance, the so-called texture.

In the method according to the invention the term "electronic imaging device" stands for all devices with which an electronic image can be recorded that can be processed with the aid of a computer. Examples of such electronic imaging devices are digital recording devices. Preferably, the electronic imaging device is a digital video camera, a digital camera, a flatbed scanner, a drum scanner, or a manually operated scanner. However, an analogue video camera coupled to a so-called frame grabber which converts the analogue signal to a digital image is also covered by the term "electronic imaging device." Finally, the term "electronic imaging device" also covers multi-spectral-imaging equipment and monochrome cameras with multiple colourcolor filters. Examples of flatbed scanners are the Hewlett Packard 3C, Hewlett Packard Scanjet IIc, Sharp JX450, Agfa Focus Color, and Afga Arcus Plus. Examples of drum scanners are the Howtek D4000, Optronics Color Getter, and LeafScan 45. Examples of

digital cameras are the Ricoh RDC 5000, Olympus C-2000Z, and Nikon Coolpix 950. Preferably, a digital camera is employed.

A minimum of two calibration eeleurcolors is used, i.e. white and black. Optionally, use may be made of grey or neutral eeleurcolors. For a more accurate conversion of the eeleurcolor signals of the selected eeleurcolor to colorimetric data preference is given to including calibration eeleurcolors other than the neutral eeleurcolors. The calibration eeleurcolors may be selected at random. Preferably, use is made of calibration eeleurcolors distributed over the entire colorimetric eeleurcolor space. More preferably, use is made of calibration eeleurcolors distributed in the vicinity of the selected eeleurcolor.

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In theory, the physical calibration pattern can comprise as many calibration eoleurcolors as may be present within the image field of the electronic imaging device. The calibration eoleurcolors are recorded on the pattern in the form of patches. In theory, the calibration patches may have the size of a single pixel. In that case the size of the measuring surface will be equal to the size of the calibration patch. Depending on the electronic imaging device employed, phenomena may occur which require the calibration patch to be bigger than a single pixel. Such phenomena include stability, non-linearity, distortions, reproducibility of positioning, and cross-talk. Generally speaking, between 2 and 1000 calibration eoleurcolors may be present, preferably 10-500, more preferably 25-150.

Of course, the calibration patches need not be square. Nor do they have to be rectangular or regularly shaped. There is no need to separate the <u>colourcolor</u>s, i.e. the <u>colourcolor</u> is allowed to shift gradually.

The support on which the calibration patches are provided may be flat or curved. Preferably, the support is of uniform colourcolor, e.g., white or grey. A

ACO 2733US Serial No. 09680089

clear space may be left around a portion or all of the calibration patches so as to leave the support's surface area visible. The uniform <u>eelourcolor</u> of the support may also serve to measure and correct any spatial non-uniformity of the electronic imaging device.

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Depending on the measuring accuracy required, it may be preferred to measure the calibration eleurcolors and the selected eleurcolor simultaneously. In such cases the calibration pattern support may be provided with a recess, e.g., at the centre. Alternatively, a support may be selected which is smaller than the image field, so that the remaining image field can be used to record the selected eleurcolor.

Also, within the framework of the present invention it is possible to calibrate beforehand in step a) using a calibration pattern with more than 10 colourcolors, then in step b) carry out a black and white calibration and measure the selected colourcolor simultaneously. This combination of steps is useful in reducing the variation in brightness due to the influence of the light source.

Processing the recorded image, calculating the model parameters, and converting the measured eeleurcolor signals to colorimetric data is all done by means of computer software. The software indicates the position of the calibration pattern and, optionally, the object to be measured. The software also includes a table listing known colorimetric data for each calibration eeleurcolor and a mathematical model describing the correlation between the measured eeleurcolor signals and the colorimetric data. With the aid of the software the model parameters are calculated from the mathematical model. The software then goes on to use the mathematical model and the model parameters to convert the measured signals of the selected eeleurcolor to colorimetric data.

Colorimetric data may be exemplified by CIE systems such as Lab or XYZ. However, this term is not restricted to CIE systems. It may be possible to use user defined systems.

The mathematical model selected may be any model known to the skilled person. Examples are mentioned in H.R. Kang, *Color Technology for Electronic Imaging Devices*, SPIE Optical Engineering Press, 1997, chapters 3 and 11, and in U.S. 5,850,472. The model may be non-linear or linear. One example of a non-linear model is a 2nd order polynomial having 10 parameters or a 3rd order polynomial having 20 parameters. Preferably, use is made of a linear model. More preferably, the linear model used has 4 model parameters.

One example of a linear model having 4 parameters is the following model, where the measured eolourcolor signals of the calibration eolourcolors, in this case R, G, and B data, are converted to colorimetric data, in this case CIELab data:

$$L_i^*=c_0+c_1R_i+c_2G_i+c_3B_i$$
,
 $a_i^*=d_0+d_1R_i+d_2G_i+d_3B_i$,
 $b_i^*=e_0+e_1R_i+e_2G_i+e_3B_i$,

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wherein R_i, G_i, B_i, L_i*, a_i*, and b_i* are the measured signals and the colorimetric data of calibration eleurcolor i.

Linear regression is used to calculate the model parameters c₀-c₃, d₀-d₃, and e₀-e₃ from the measured RGB data and the known CIELab data of the calibration eoleurcolors. These model parameters are used to convert the measured RGB data of the selected eoleurcolor to CIELab data.

One example of a non-linear 3rd order polynomial having 20 parameters is:

$$L_{i}^{\star} = c_{0} + c_{1}R_{i} + c_{2}G_{i} - c_{3}B_{i} + c_{4}R_{i}^{2} + c_{5}G_{i}^{2} + c_{6}B_{i}^{2} - c_{7}R_{i}G_{i} - c_{8}R_{i}B_{i} + c_{9}G_{i}B_{i} + c_{10}R_{i}^{3} + c_{11}G_{i}^{3} + c_{12}B_{i}^{3} + c_{13}R_{i}^{2}G_{i} + c_{14}R_{i}^{2}B_{i} + c_{15}G_{i}^{2}R_{i} + c_{16}G_{i}^{2}B_{i} + c_{15}G_{i}^{2}R_{i} + c_{16}G_{i}^{2}B_{i} + c$$

$$c_{17}B_i^2R_i + c_{18}B_i^2G_i + c_{19}R_iG_iB_i$$

$$a_{i}^{*} = d_{0} + d_{1}R_{i} + d_{2}G_{i} - d_{3}B_{i} + d_{4}R_{i}^{2} + d_{5}G_{i}^{2} + d_{6}B_{i}^{2} - d_{7}R_{i}G_{i} - d_{8}R_{i}B_{i} + d_{9}G_{i}B_{i} + d_{10}R_{i}^{3} + d_{11}G_{i}^{3} + d_{12}B_{i}^{3} + d_{13}R_{i}^{2}G_{i} + d_{14}R_{i}^{2}B_{i} + d_{15}G_{i}^{2}R_{i} + d_{16}G_{i}^{2}B_{i} + d_{17}B_{i}^{2}R_{i} + d_{18}B_{i}^{2}G_{i} + d_{19}R_{i}G_{i}B_{i}$$

$$\begin{aligned} 5 & b_i{}^* = & e_0 + e_1 R_i + e_2 G_i - e_3 B_i + e_4 {R_i}^2 + e_5 {G_i}^2 + e_6 {B_i}^2 - e_7 R_i G_i - e_8 R_i B_i + e_9 G_i B_i + e_{10} {R_i}^3 + e_{11} {G_i}^3 + e_{12} {B_i}^3 + e_{13} {R_i}^2 G_i + e_{14} {R_i}^2 B_i + e_{15} {G_i}^2 R_i + e_{16} {G_i}^2 B_i + e_{17} {B_i}^2 R_i + e_{18} {B_i}^2 G_i + e_{19} R_i G_i B_i \end{aligned}$$

Linear regression is used to calculate the model parameters c₀-c₁₉, d₀-d₁₉, and e₀-e₁₉ from the measured RGB data and the known CIELab data of the calibration colourcolors. These model parameters are used to convert the measured RGB data of the selected colourcolor to CIELab data.

Notwithstanding the above, it is possible to lend greater weight to the calibration eeleurcolors in the vicinity of the selected eeleurcolor when calculating the model parameters. In the case of the above example of a linear model having 4 parameters, this means that during the linear regression each calibration eeleurcolor is given a weighing factor based on the distance in the RGB eeleurcolor space between the calibration eeleurcolor in question and the selected eeleurcolor. In the linear regression procedure the following sum of squares is minimised:

$$\sum_{i=1}^{n} w_{i} (y_{i} - \hat{y}_{i})^{2}$$

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Written out, this sum is as follows:

$$\sum_{i=1}^{n} \left(L_{i}^{*} - C_{0} - C_{1}R_{i} - C_{2}G_{i} - C_{3}B_{i} \right)^{2} \left(\left(R_{i} - R \right)^{2} + \left(G_{i} - G \right)^{2} + \left(B_{i} - B \right)^{2} \right)^{-2}$$

$$\sum_{i=1}^{n} \Bigl(\!a_{i}^{*} - d_{0}^{} - d_{1}^{}R_{i}^{} - d_{2}^{}G_{i}^{} - d_{3}^{}B_{i}^{}\bigr)^{2} \Bigl(\!(\!R_{i}^{} - R^{}\bigr)^{2} + \bigl(\!G_{i}^{} - G^{}\bigr)^{2} + \bigl(\!B_{i}^{} - B^{}\bigr)^{2}\Bigr)^{\!-2}$$

$$25 \qquad \sum_{i=1}^{n} \left(\!b_{i}^{*} - e_{o} - e_{i}R_{i} - e_{2}G_{i} - e_{3}B_{i}\right)^{\!2} \left(\!\left(\!R_{i} - R\right)^{\!2} + \!\left(\!G_{i} - G\right)^{\!2} + \!\left(\!B_{i} - B\right)^{\!2}\right)^{\!-2}$$

wherein

n: is the number of calibration colourcolors

R, G, B: are the measured signals of the selected colourcolor

Alternatively, it is possible to use the calibration eolourcolors in the vicinity of the selected eolourcolor for interpolation.

If so desired, grey balancing may be performed on the signals measured for black, white, and grey according to the formula R=G=B=f(L*) or a comparable value for L* in a different colorimetric system. Such grey balancing is described in H.R. Kang, *Color Technology for Electronic Imaging Devices*, SPIE Optical Engineering Press, 1997, chapter 11. Examples of algorithms suitable for use are:

$$R_{ig} = f_1 + f_2 \cdot L_{ig}^*$$

$$R_{ig} = f_1 + f_2 \cdot L_{ig}^* + f_3 \cdot (L_{ig}^*)^2$$

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$$R_{iq} = f_1 + f_2 \cdot L_{iq} + f_3 \cdot \log(L_{iq})$$

wherein R_{ig} is the measured signal and L_{ig}^* is the colorimetric value of the white, grey, and black calibration <u>colour</u>colors.

Alternatively, if so desired, an offset correction of the measured data for black and white may be performed according to the following formula:

$$R_{c} = ((R - R_{b})/(R_{w} - R_{b})) \times 255$$

$$G_{c} = ((G - G_{b})/(G_{w} - G_{b})) \times 255$$

$$B_{c} = ((B - B_{b})/(B_{w} - B_{b})) \times 255$$

wherein

 R_c , G_c , B_c = the corrected signals for the selected colourcolor

R, G, B = the measured signals for the selected colourcolor

25 R_w , G_w , B_w = the measured signals for white

 R_b , G_b , B_b = the measured signals for black

In the final step of the method according to the invention a databank is used to determine a eolourcolor formula having colorimetric data most closely matching the calculated colorimetric data of the measured selected eolourcolor. One measure of the eolourcolor difference between the eolourcolor formula and the selected eolourcolor is, e.g., the following mathematical algorithm:

$$\Delta E *_{ab} = \sqrt{\left(\Delta L *)^2 + \left(\Delta a *)^2 + \left(\Delta b *\right)^2\right)}$$

wherein

ΔE*_{ab} is the colourcolor difference according to CIE

$$\Delta L^* = L^*_1 - L^*_2$$

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$$\Delta a^* = a_1^* - a_2^*$$

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$$\Delta b^* = b_1^* - b_2^*$$

2 = the colorimetric data of the colourcolor formula from the databank

The smaller the colourcolor difference ΔE_{ab}^{*} is, the better the match between the selected colourcolor and the colourcolor formula will be.

Colour Color formulas can be determined in a number of ways, i.e. by means of search procedures, calculations, or combinations of the two. For example, use may be made of a databank comprising eolour formulas having colorimetric data linked thereto. Using the calculated colorimetric data of the measured selected eolour color, the most closely matching eolour formula can be found. Alternatively, it is possible to use a databank having eolour formulas with spectral data linked thereto. Known calculation methods can be used to calculate the colorimetric data of the eolour formulas and compare them. Also, a databank can be used in which the absorption and reflection data, the so-called K and S data, of pigments are stored. Using K and S data in combination with pigment concentrations makes it possible to calculate the eolour formula of which the colorimetric data most closely match the colorimetric data of the measured selected eolour color. The methods in

question have been described in detail in D.B. Judd et al., *Color in Business, Science and Industry*. It is possible to combine the aforesaid search and calculation methods.

5 Phenomena such as light source metamerism, angular metamerism, and texture will affect the celourcolor matching.

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Light source metamerism is a phenomenon where under a single light source, e.g., daylight, the observed eeleurcolors of two objects may be the same visually, while under some other light source, e.g., fluorescent light, the eeleurcolors differ. This can be taken into account by measuring under two light sources with different emission spectra. In the method according to the invention, advantageous use is made of an electronic imaging device, with recordings being made of the selected eeleurcolor and the calibration eeleurcolors under different light sources. The software needed to process different measurements of the same object is known to the skilled person.

Textured materials, such as metallic and pearlescent paints, are characterised in that the appearance of the colourcolor changes as the angle of observation and/or exposure angle changes (angular metamerism). For proper measurement of such colourcolors it is therefore essential to determine the colourcolor at at least two different angles. In this process it is advantageous to make use of the method according to the invention. An electronic imaging device makes it possible to measure the colourcolor of an object in any one of the following ways or combinations thereof:

- At least two recordings are made with the electronic imaging device while the object moves within the image field of the device;
- At least two recordings are made with the electronic imaging device while the device moves vis-à-vis the object;

- At least two recordings are made with the electronic imaging device while a light source is moved vis-à-vis the object; or
- One recording is made with the electronic imaging device of a flat or curved section of the object when the device is able to discriminate in a single image between data at different angles.

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The software required to process different measurements of the same object is known to the skilled person.

Another characteristic of materials, such as special effect paints, is texture.

Texture can be defined as an arrangement of small areas having a specific eleurcolor and/or shape. It was found that by using image processing methods known as such the texture of a special effect paint can be determined from recordings made with an electronic imaging device. One way of characterising texture is by means of texture parameters. Commercially available image processing packages, e.g., "Optimas," make it possible to calculate such texture parameters using the recording. An example of such calculations is given below. Needless to say, said example should not be construed as limiting the present invention in any way.

The recording of the measured selected colourcolor is used to determine the average brightness. Selected are areas in the recording which have much higher than average brightness. If so desired, it can be determined which areas overlap or adjoin and to separate those areas using software. Each selected area has its circumference and surface area calculated. This gives the average circumference, the average surface area, and the accompanying standard deviations for the measured selected colourcolor. Optionally, calculations such as averaging and filtering pixels and/or pixel groups may also be included.

If so desired, the texture measurement can be calibrated by applying one or more rulers to the calibration pattern. For matching textured materials such as special effect paint, the method according to the invention provides the possibility of linking the eeleurcolor formulas in a databank not only to colorimetric data but also to texture parameters or recordings from which texture parameters can be calculated. Using these parameters or recordings the eeleurcolor formula most closely matching the selected eeleurcolor also in terms of texture can be found in the databank. One example of an algorithm for finding the most closely matching eeleurcolor formula which is also closest to the selected eeleurcolor in terms of texture is as follows:

$$\Delta T = \sqrt{\mathbf{w}_1 \Delta T_1^2 + \mathbf{w}_2 \Delta T_2^2 + \dots + \mathbf{w}_i \Delta T_i^2}$$

wherein

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w_{1-i} = weighing factors

T_{1-i}= texture parameters

15 It is also possible to calculate an overall parameter, e.g. $\Delta Q = f(\Delta E, \Delta T)$.

The method according to the invention can be applied at points of sale which have to be able to supply paint in any eeleurcolor desired. A eeleurcolor formula is made up of quantities of mixing eeleurcolors, master paints and/or pigment pastes. Using the eeleurcolor formula, the paint can be prepared in a dispenser. In the car repair sector it is customary to employ a set of mixing eeleurcolors standardised for eeleurcolor and eeleurcolor strength. These standardised mixing eeleurcolors, usually about 40 different eeleurcolors, are present at the points of sale. From this set of standardised mixing eeleurcolors any eeleurcolor of paint desired can be made. In the DIY sector as well as the professional painting industry it is customary to use a set of master paints standardised for eeleurcolor which often consists of at least one white and/or one clear master eeleurcolor, i.e. a paint without pigment, optionally supplemented with master paints in a number of different eeleurcolors, and pigment pastes standardised

for eolourcolor and eolourcolor strength. From this set of master paints any eolourcolor desired can be made by adding pigment pastes to the master paint.

The present invention can be used with advantage in the car repair industry. In that case, the method may be carried out as follows. The eleurcolor of a car to be repaired is measured using an electronic imaging device. Prior to this or at the same time, a recording is made of a panel on which different calibration eleurcolors have been applied. The colorimetric data of the car's eleurcolor is calculated. Software is used to generate the eleurcolor formula which after application will give a eleurcolor identical to the eleurcolor of the car to be repaired. The eleurcolor formula is prepared in a dispenser and applied.

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As stated above, it may be advantageous to perform the calibration electrolors measurement simultaneously with the measurement of the selected electrolor. This is the case for instance in the car auto repair industry, where a measuring accuracy of a ΔE_{ab}^* smaller than 1 is required. In that case the method can be carried out such that in one image both a section of the car and the panel with the calibration electrolors are measured. The process does not require that the calibration panel is actually positioned on the car. It may be mounted somewhere else, providing it is in the same image field as the car during the recording.

Optionally, other information may be provided to be recorded with the electronic imaging device. For example, when several patterns are used, a code may be provided on every pattern. When the method of the invention is used in the car industry, information may be provided with regard to the type of car, its year of manufacturing, and other relevant information. This information may be provided in the form of bar codes, dot codes, or alpha-numerical information. A space may be provided on the calibration pattern for this kind of information.

However, it is also possible to provide this information at any other place in the body shop as long as it is in the same image field as the car.

Since it has now proved possible to also measure the texture of an object with an electronic imaging device, the invention also comprises a method of determining a electronic formula for matching a selected electronic of textured materials such as special effect paints in which

- a) the selected colourcolor is measured with a spectrophotometer or tristimulus meter;
- 10 b) the texture of the selected colour<u>color</u> is measured with an electronic imaging device; and
 - c) the measured eoleurcolor and texture signals are used to determine, in a databank, the eoleurcolor formula of which the colorimetric data and the texture parameters most closely match those of the selected eoleurcolor.

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It is well-known to use a spectrophotometer for measuring a selected eolourcolor of a special effect paint and use the spectral measuring data to find the eolourcolor formula most closely matching the selected eolourcolor in a databank. Such databanks often will have a texture parameter linked to the eolourcolor formula, i.e. coarseness, frequently expressed in a numerical range, such as from 0 to 10. This parameter is indicated by the user, who with the aid of swatches will determine the coarseness of the special effect paint at sight. Using a method according to the invention, it is now possible to determine the texture electronically, convert it to a coarseness value, and use this value to find a eolourcolor formula in an existing databank which most closely matches the selected eolourcolor.

Alternatively, of course, databanks can be adapted or new ones set up in which new texture parameters or recordings are linked to eeleurcolor formulas.

Since special effect paints are used primarily on cars, the above methods are preferably used in the car repair industry.

Finally, the invention pertains also to a method of determining the colour difference of a selected colour measured with an electronic imaging device compared to a standard colour sample, which method comprises the following steps:

- a) an electronic imaging device is calibrated by measuring the eelourcolor signals of at least two calibration eelourcolors, the colorimetric data of
 each of the calibration eelourcolors being known;
 - b) at the same time or in a next step the selected eolourcolor is measured with the aid of the electronic imaging device;
- using a mathematical model, parameters are calculated for converting the measured eoleurcolor signals of the calibration eoleurcolors to the known colorimetric data;
 - using the mathematical model and the calculated parameters, the colourcolor signals of the measured selected colourcolor are converted to colorimetric data; and
- e) the colorimetric data of the selected colourcolor are compared to the colorimetric data of a standard colourcolor sample.

The colorimetric data of the standard colourcolor sample can be available in a software program. It is also possible to measure the standard colourcolor sample before, simultaneously, or after the measurement of the selected colourcolor. This method is preferably used in the printing inks industry.

All three methods of the present invention are not restricted to but are preferably used in the paint or printing inks industry.

30 The invention will be elucidated with reference to the following examples.

Examples

The measurements in these examples were performed using two different calibration patterns, both on an A4-size support. The calibration eolour colors of the two calibration patterns first had their colorimetric data determined with the aid of spectrophotometers:

Calibration pattern 1 (see figure 1):

- 65 calibration colourcolors distributed over the entire colourcolor space
- The colourcolors are from the Sikkens 3031 Color Collection

The L*, a*, and b* data of the 65 calibration eolourcolors were measured with the HunterLab UltraScan spectrophotometer with D/8 geometry. The L*, a*, and b* (daylight D65, 10°-observer) data is listed in Table 1.

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Calibration pattern 2 (see figure 2):

- 37 calibration eeleurcolors distributed over part of the eeleurcolor space (0<a*<50; 0<b*<50; 15<L*<65). The neutral eeleurcolors (white/ grey/ black) are present in duplicate (eeleurcolor nos. 1, 2, 6, 7, 8, 13, 14, 15, 18, and 19).
- The colourcolors are selected from the Sikkens Car Refinishes Color Map (Autobase colourcolors)

The 37 calibration eolourcolors were measured with different spectrophotometers, among others the Macbeth CE 730-GL, at three angles, 45/0, 45/20, and 45/-65 geometry. The spectral data was transformed mathematically to D/8 geometry. The calculated L*, a*, and b* (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer) data is listed in Table 2.

30 Example 1

A Hewlett Packard 3C flatbed scanner was used to measure the colourcolor of calibration pattern 1 and 149 unknown colourcolors. The method involved each unknown colourcolor being measured simultaneously with the calibration pattern. The result of the measurements in other words was 149 colourcolor images of calibration pattern 1, each time with one of the 149 unknown colourcolors in the position of the unknown colourcolor (see pattern 1, "unknown"). Using the linear model with 4 parameters and the weighing algorithm as described above, the colorimetric data of the 149 unknown colourcolors was calculated.

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In addition, the colorimetric data of the 149 unknown eeleurcolors was measured with the aforesaid Hunterlab Ultrascan spectrophotometer with D/8 geometry (daylight D65, 10°-observer).

Table 3 presents a survey of the data. Columns 2-4 list the colorimetric data as measured with the spectrophotometer, columns 5-7 list the colorimetric data as measured using the scanner, and column 8 lists the eeleurcolor differences between the spectrophotometer and the scanner colorimetric data. On average, the eeleurcolor difference ΔE ab = 2,26. The median of the eeleurcolor difference ΔE ab = 1,67. The ΔE ab s are also listed in Table 4.

Example 2

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Example 1 was repeated, except that the measurement of the calibration pattern took place beforehand. In other words, the outcome of the measurements was one recording of calibration pattern 1 and 149 recordings of the unknown colourcolors without calibration pattern 1.

A survey of the results is also to be found in Table 3. Columns 9-11 list the colorimetric data as determined with the scanner. Column 12 lists the eolourcolor difference between the colorimetric data determined with the

spectrophotometer and those determined with the scanner. On average, the $\frac{\text{colour}}{\text{color}}$ difference ΔE_{ab}^* = 2,23. The median of the $\frac{\text{colour}}{\text{color}}$ difference ΔE_{ab}^{\dagger} = 1,61. The ΔE_{ab}^{\dagger} 's are also listed in Table 4.

5 Examples 3 and 4

Examples 1 and 2 were repeated, except that also grey balancing was performed using the following algorithm R_{ig} = $f_1+f_2\cdot L_{ig}^{\star}$. The results are listed in Table 4.

10 Example 5

Example 1 was repeated, except that there was no weighing. The results are listed in Table 4.

Example 6

15 Example 5 was repeated, except that use was made of the model with 20 parameters as described in the text. The results are listed in Table 4.

Discussion of Examples 1-6

As is clear from Table 4, Examples 1-6 show that good results can be obtained using the method according to the invention. Depending on the required accuracy, it is possible to choose among the different algorithms. It is clear from Examples 5 and 6 that a method according to the invention can be performed by simultaneously calibrating and employing a model with 4 or 20 parameters. Also, it is shown in Examples 1-2 and 3-4 that there is hardly any difference 25 between calibrating beforehand and simultaneous calibration. This is probably the result of a combination of factors, i.e. the use of the calibration pattern with 65 colourcolors, the mathematical model, and the Hewlett Packard 3C flatbed scanner. It is expected that a change of one or more of these factors will show better results in the simultaneous calibration than in calibrating beforehand.

Example 7

Using a Hewlett Packard Scanjet 5P flatbed scanner, the eolourcolor was measured of calibration pattern 2 and 28 unknown eolourcolors, in each case with the unknown eolourcolor being measured simultaneously with the calibration pattern. The result of the measurements thus was 28 eolourcolor images of calibration pattern 2, each time with one of the 28 unknown eolourcolors in the position of the unknown eolourcolor (see pattern 2, "unknown"). Using the linear model with 4 parameters and the weighing algorithm as described in the text above, the colorimetric data of the 28 unknown eolourcolors was calculated.

In addition, the colorimetric data of the 28 unknown eleurcolors was calculated by measuring the eleurcolors with the aid of a MacBeth CE 730-GL spectrophotometer, at three angles, 45/0, 45/20, and 45/-65 geometry (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer) and transforming the spectral data mathematically to D/8 geometry.

Table 5 presents a survey of the measuring data. Columns 2-4 list the colorimetric data as measured with the spectrophotometer, columns 5-7 list the colorimetric data as measured with the scanner, and column 8 lists the colorimetric data as measured with the scanner, and column 8 lists the colorimetric differences between the spectrophotometer and the scanner colorimetric data. On average, the colourcolor difference $\Delta E_{ab}^* = 2,20$. The median of the colourcolor difference $\Delta E_{ab}^* = 2,04$. The ΔE_{ab}^* is are also listed in Table 6.

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Example 8

Example 7 was repeated, except that the measurement of the calibration pattern took place beforehand. The outcome of the measurements, in other words, was one recording of calibration pattern 2 and 28 recordings of the unknown colourcolors without calibration pattern 2.

ACO 2733US Serial No. 09680089

A survey of the results is also to be found in Table 5. Columns 9-11 list the colorimetric data as determined with the scanner. Column 12 lists the colourcolor difference between the colorimetric data determined with the spectrophotometer and those determined with the scanner. On average, the colourcolor difference $\Delta E_{ab}^* = 2,24$. The median of the colourcolor difference $\Delta E_{ab}^* = 2,18$. The ΔE_{ab}^* 's are also listed in Table 6.

Examples 9 and 10

Examples 7 and 8 were repeated, except that also grey balancing was performed using the following algorithm $R_{ig} = f_1 + f_2 \cdot L_{ig}^*$. The ΔE_{ab}^* is are listed in Table 6.

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Example 11

Example 7 was repeated, except that there was no weighing. The ΔE_{ab}^* 's are listed in Table 6.

10 <u>Example 12</u>

Example 11 was repeated, except that use was made of the model with 20 parameters as described in the text. The ΔE_{ab}^* 's are listed in Table 6.

Discussion of Examples 7-12

As is clear from Table 6, Examples 7-12 show that good results can be obtained using the method according to the invention. Depending on the required accuracy, it is possible to choose among the different algorithms. It is clear from Examples 11 and 12 that a method according to the invention can be performed by simultaneously calibrating and employing a model with 4 or 20 parameters.

Also, it is shown in Examples 7-8 and 9-10 that there is hardly any difference between calibrating beforehand and simultaneous calibration. This is probably the result of a combination of factors, i.e. the use of the calibration pattern with 37 eeleurcolors, the mathematical model, and the Hewlett Packard Scanjet 5P flatbed scanner. It is expected that a change of one or more of these factors will show better results in the simultaneous calibration than in calibrating

beforehand.

Example 13: Reproducibility

One of the 65 calibration patches of pattern 1 (no. 8) was designated as an unknown colourcolor. The colorimetric data of the selected colourcolor was $L^*=36,56$; $a^*=56,40$; and $b^*=42,10$.

Calibration patch 8 was measured 149 times with the Hewlett Packard 3C flatbed scanner, simultaneously with the 64 known calibration eeleurcolors. The standard deviation in ΔE ab measured over the 149 measuring points was 0,35, which is comparable with the result for a spectrophotometer.

10 Example 14: Reproducibility

On eof the 37 calibration patches of pattern 2 (no. 26) was designated as an unknown eolourcolor. The colorimetric data of the selected colourcolor was L*=34,29; a*=37,55; and b*=33,64.

Calibration patch 26 was measured 28 times with the Hewlett Packard 3C flatbed eoleurcolors scanner, simultaneously with the 36 known calibration patches. The standard deviation of ΔE ab measured over the 28 measuring points was 0,17, which is of the same order of magnitude as when a spectrophotometer is used.

Table 1

Colorimetric data of calibration pattern 1 measured with the Hunterlab spectrophotometer (daylight D65, 10°-observer)

Calibration	Mea	sured data	(CIE)
patch	L*	a*	b*
1	23,67	31,31	10,69
2	56,60	34,49	13,98
3	50,48	46,72	18,74
4	46,72	53,20	23,01
5	18,33	13,52	8,22
6	39,86	43,11	30,76
7	34,44	46,89	35,06
8	36,56	56,40	42,10
9	39,04	57,47	45,18
10	35,57	32,99	31,27
11	75,67	20,82	29,39
12	57,50	43,64	62,68
13	45,90	18,78	39,32
14	33,76	7,97	17,87
15	70,84	31,22	92,17
16	89,07	5,42	21,46
17	46,29	9,96	46,57
18	68,95	16,82	80,15
19	40,73	3,70	21,99
20	75,78	11,24	91,04
21	85,14	3,28	57,41
22	87,63	8,71	2,00
23	84,96	7,26	12,81
24	90,59	-0,42	6,25
25	89,13	-1,27	1,02
26	88,89	-7,82	-1,62
27	85,73	1,84	-8,11
28	29,52	6,54	0,72
29	21,56	2,52	4,84
30	36,55	0,89	7,92
31	60,78	-3,08	6,28
32	95,23	-0,91	0,93
33	24,68	-6,48	1,02
34	80,28	-0,13	0,06
35	60,92	-0,20	0,27
36	23,45	-0,45	-0,73
37	30,50	0,26	-0,01
38	16,97	0,31	1,37

ACO 2733US Serial No. 09680089

Calibration	Mea	sured data	(CIE)	
patch	L*	a*	b*	
39	64,60	1,22	67,45	
40	27,26	-4,14	20,17	
41	54,33	-14,23	51,54	
42	85,41	-14,22	26,69	
43	60,75	-12,09	15,68	
44	12,02	-0,39	-0,62	
45	48,45	-24,08	29,04	
46	27,35	-8,37	8,95	
47	79,80	-12,99	14,65	
48	63,89	-41,61	38,05	
49	35,93	-13,81	8,00	
50	40,96	-34,26	11,19	
51	35,75	-38,78	0,48	
52	55,84	-19,84	-5,48	
53	26,09	-9,59	-5,56	
54	18,92	-8,61	-8,01	
55	74,36	-14,83	-15,11	
56	46,17	-29,05	-25,64	
57	15,61	-6,47	-10,57	
58	57,39	-10,71	-17,84	
59	35,59	-12,07	-29,64	
60	34,45	-12,38	-37,92	
61	43,42	-4,46	-22,82	
62	34,21	-0,57	-34,86	
63	46,34	7,69	-32,94	
64	65,16	15,14	-7,60	
65	43,99	22,89	-14,27	

Table 2

Colorimetric data of calibration pattern 2 measured with a spectrophotometer (scanner light source of the Hewlett Packard Scanjet 5P flatbed scanner, 10°-observer)

Calibration	Measured data (CIE)							
patch	L*	a*	b*					
1	17,00	-0,07	-0,34					
2	26,13	-0,04	-0,20					
3	59,55	6,39	43,02					
4	44,03	7,81	44,48					
5	40,03	8,02	27,87					
6	62,52	-0,50	-0,25					
7	42,18	0,09	-0,21					
8	17,00	-0,07	-0,34					
9	59,01	9,63	26,03					
10	29,16	8,09	21,43					
11	38,01	30,08	35,37					
12	39,96	8,00	35,05					
13	87,99	-0,35	-0,08					
14	26,13	-0,04	-0,20					
15	42,18	0,09	-0,21					
16	57,48	20,93	39,01					
17	45,24	22,82	39,82					
18	62,52	-0,50	-0,25					
19	87,99	-0,35	-0,08					
20	28,77	21,89	23,23					
21	39,85	41,15	41,44					
22	39,16	25,28	24,48					
23	61,21	22,30	22,38					
24	59,28	42,37	39,71					
25	24,05	7,78	9,13					
26	34,29	37,55	33,64					
27	44,14	42,56	26,06					
28	54,09	42,16	25,65					
29	40,45	9,54	6,44					
30	58,95	8,08	7,83					
31	28,76	43,21	23,63					
32	22,42	24,71	9,62					
33	40,61	27,92	9,67					
34	25,48	39,71	9,94					
35	56,69	26,87	6,45					
36	43,08	40,55	4,95					
37	57,23	41,44	7,64					

ACO 2733US Serial No. 09680089

Table 3
Measuring data of Examples 1 and 2

		orimetric		Sir	multaneo	ous		Calibr	ation pre	cedes	-
		asured w			asuring			j n	neasurin	9	
Colour		trophoto			alibratio					r: - ·	
Colour Color	L*-ref	a*-ref	b*-ref	L*-real	a^-real	b*-real	1 "	L*-sing	a*-sing	b*-sing	ΔE* _{ab}
1	49,71	6,26	0.11	E0 62	6.02	0.00	real	50.62	0.00	0.00	sing
2	13,27	5,73	0,11	50,63	6,92	0,86	1,36	50,63	6,92	0,86	1,36
3	12,29	17,25	2,18 2,74	15,40 17,00	3,76	3,42	3,15	15,19	3,74	3,32	2,99
4	75,11	8	3,69	75,84	18,13 8,14	8,93	7,82	15,82	17,62	7,81	6,19
5	43,97	51,03	15,41	43,88	51,53	4,54 13,73	1,13 1,75	75,70 43,23	7,90	4,81	1,27
6	17,4	24,77	10,24	21,85	30,74	19,46	11,85	21,35	50,34 29,57	12,91	2,70
7	25,19	42,36	21,41	29,51	43,82	30,29	9,99	28,22	42,74	18,16	10,07
8	21,8	2,56	1,53	21,47	3,12	4,07	2,62	21,19	3,35	28,54	7,75 3,14
9	15,25	15,84	7,62	17,29	13,49	9,31	3,54	16,45	12,63	4,51 7,73	
10	34,81	48,8	29,69	36,16	49,38	33,94	4,50	36,27	48,40	32,83	3,43 3,49
11	28,71	49,11	30,31	32,81	49,99	37,88	8,65	31,85	48,86	35,69	6,23
12	22,61	27,71	19,84	22,38	26,01	19,17	1,84	21,21	25,84	17,42	3,36
13	28,01	32,31	23,89	26,97	31,06	23,97	1,63	26,25	29,93	22,82	3,15
14	33,22	50,72	37	33,93	51,63	39,50	2,75	33,00	50,40	37,51	0,64
15	82,74	3,55	3,88	83,33	4,56	5,40	1,92	82,89	4,56	5,76	2,14
16	60,42	24,02	22,39	59,17	25,76	19,18	3,86	58,93	24,67	18,77	3,97
17	45,95	24,87	24,61	46,37	24,88	27,82	3,24	45,88	23,54	26,66	2,44
18	43,89	40,09	38,78	48,04	40,80	51,49	13,39	47,48	39,41	50,14	11,93
19	92,39	1,06	3,49	93,71	0,91	2,93	1,44	92,99	1,08	3,31	0,62
20	89,56	4,09	6,44	89,97	4,39	6,68	0,56	89,66	3,98	6,58	0,21
21	86,08	6,9	7,99	86,57	7,62	9,67	1,90	86,23	7,17	9,54	1,58
22	22,57	4,8	6,06	22,31	4,82	7,16	1,14	22,26	4,76	6,96	0,95
23	45,1	7,29	7,86	45,77	7,06	6,39	1,63	45,43	6,42	6,48	1,67
24	75,62	11,53	12,94	75,48	11,59	12,55	0,42	75,12	10,78	12,20	1,17
25	20,1	10,87	10,38	21,58	11,03	11,66	1,96	20,87	10,12	10,39	1,08
26	54	22,28	26,15	55,73	22,25	28,69	3,07	55,44	20,63	27,75	2,72
27	27,56	15,78	18,83	29,02	14,97	21,38	3,05	28,33	14,92	20,43	1,98
28	71,6	4,45	6,08	71,62	4,10	5,75	0,48	71,15	3,60	5,88	0,98
29	88,36	5,09	7,67	88,92	5,33	9,50	1,93	88,52	5,08	9,14	1,48
30	66,31	8,14	11,37	66,53	7,89	11,49	0,35	66,26	7,04	11,45	1,10
31	80,62	12,48	16,75	80,91	12,77	17,68	1,02	80,77	11,85	17,29	0,84
32	8,42	0,57	-0,11	13,47	-0,12	0,05	5,10	12,91	0,16	-0,24	4,51
33	52,34	2,7	5,87	53,51	2,96	6,10	1,23	53,31	2,18	6,31	1,19
34	34,61	6,16	11,87	35,29	6,25	14,68	2,89	35,26	5,53	14,81	3,08
35	27,7	13,56	22,8	29,83	13,66	24,38	2,65	29,47	13,08	23,47	1,95
36	56,51	9,55	21,34	56,69	9,46	19,03	2,32	56,61	9,41	18,95	2,40
37	25,48	1,29	4,75	24,42	1,29	5,55	1,33	24,28	0,82	6,06	1,84
38	80,87	4,88	14,71	81,05	5,35	15,48	0,92	80,71	5,04	15,45	0,77
39	64,96	8,09	23,33	65,17	8,23	22,80	0,58	65,05	7,65	22,88	0,64
40	70,72	13,31	42,15	70,81	12,61	41,30	1,10	70,78	11,54	40,89	2,17
41	51,9	18,98	54,91	53,83	18,12	62,24	7,63	53,87	17,18	62,55	8,09
42	65,68	2,34	9,17	66,02	2,31	9,82	0,73	65,89	1,95	10,19	1,11

ACO 2733US Serial No. 09680089

	Cole	orimetric	data	Sii	multaneo	ous	<u> </u>	Calibr	ation pre	cedes	
	mea	asured w	ith a	me	asuring	and		n	neasurin	g	
		trophoto			alibratio						
Colour	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real	ΔE* _{ab} -	L*-sing	a*-sing	b*-sing	ΔE* _{ab}
Color		<u> </u>					real				sing
43	52,47	2,46	9,1	52,56	2,64	7,81	1,30	52,82	1,95	8,09	1,19
44	89,61	4,12	14,61	90,63	4,20	17,04	2,63	90,35	3,87	16,42	1,98
45	84,56	7,7	26,01	84,59	7,69	26,57	0,56	84,36	7,03	25,77	0,74
46	89,79	0,81	5,19	90,27	0,74	5,92	0,87	89,78	0,97	5,96	0,79
_47	76,67	1,44	9,09	77,02	1,49	9,27	0,40	76,42	1,33	9,33	0,36
48	45,51	1,92	9,69	46,29	2,17	8,23	1,67	45,81	1,51	8,62	1,19
49	81,64	4,39	21,07	82,05	4,51	21,75	0,80	81,61	4,15	21,33	0,35
50	81,88	1,99	11,52	82,04	1,83	11,48	0,23	81,44	1,68	11,41	0,55
51	70,97	1,77	18,31	71,40	1,77	18,76	0,62	71,19	1,20	18,94	0,87
52	80,28	2,62	20,73	80,64	2,57	21,40	0,76	80,10	2,34	21,11	0,51
53	85,34	2,93	22,93	85,92	2,59	24,07	1,32	85,68	2,11	23,30	0,97
54	65,59	5,37	49,99	66,54	5,22	55,36	5,45	66,52	4,23	55,48	5,69
55	54,62	7,61	54,69	52,93	8,17	59,01	4,67	53,21	6,95	59,06	4,64
56	70,45	1,02	42,48	71,84	1,05	43,87	1,97	71,84	0,07	43,51	1,98
57	89,88	0,18	9,66	90,55	-0,04	10,52	1,11	90,15	0,15	10,16	0,57
58	88,51	0,77	13,07	89,11	0,70	14,58	1,63	88,63	0,59	13,95	0,91
59	77,02	-0,37	14,1	77,40	-0,19	14,30	0,46	76,71	-0,51	14,13	0,34
60	46,16	-0,62	20,09	46,11	-0,19	19,42	0,80	45,81	-0,92	19,70	0,60
61	78,14	-1,25	30,03	79,29	-1,13	31,39	1,78	78,76	-1,52	30,90	1,10
62	92,66	-0,15	8,14	94,21	-0,12	8,50	1,59	93,93	0,12	8,62	1,38
63	85,33	-0,16	10,42	85,99	-0,05	11,57	1,33	85,65	-0,12	11,68	1,30
64	66,7	-1,31	11,69	66,72	-1,12	12,70	1,03	66,81	-1,49	13,05	1,37
65	55,97	-1,72	9,92	56,88	-1,59	9,68	0,95	56,67	-2,35	10,19	0,98
66	45,98	-6,41	28,68	45,07	-5,61	27,82	1,48	45,32	-6,51	29,05	0,77
67	87,22	-1,25	4,43	87,59	-1,36	4,86	0,58	87,10	-1,28	4,92	0,51
68	52,72	-1,9	5,23	53,73	-1,43	5,22	1,11	53,32	-2,10	5,69	0,78
69	71,08	-1,71	5,96	71,36	-1,46	5,91	0,38	70,86	-1,95	6,30	0,47
70	30,92	-2,65	8,69	30,90	-3,12	9,87	1,27	30,76	-3,57	9,93	1,55
71	35,23	-7,34	28,35	36,88	-8,86	30,92	3,41	36,96	-9,49	31,81	4,42
72	55,65	-5,3	9,65	56,01	-5,30	8,96	0,78	55,73	-5,89	9,53	0,61
73	66,67	-5,66	9,97	66,01	-5,67	10,96	1,19	66,06	-6,09	11,48	1,68
74	75,32	-6,33	11,78	74,95	-5,62	10,93	1,17	74,20	-5,61	11,10	1,49
75	85,09	-7,32	12,63	85,21	-7,00	12,84	0,40	84,45	-6,65	13,03	1,01
76	35,1	-7,84	15,88	34,77	-9,59	16,72	1,97	34,65	-10,40	17,03	2,84
77	83,16	-4,27	6,37	84,00	-4,35	7,25	1,22	83,26	-4,15	7,53	1,17
78	57,75		6,42	58,14	-3,93	6,13	0,60	57,86	-4,41	6,64	0,28
79	43,77	-2,11	2,4	44,83	-0,79	2,25	1,70	43,86	-1,77	2,16	0,43
80		-17,03	21,53	62,46	-17,78	18,89	2,78	61,96	-18,20	19,95	2,20
81	92,95	-1,12	1,25	95,73	-0,68	1,26	2,82	94,11	-0,53	1,94	
82		-10,69	10,42		-10,21	11,20	1,07	85,06	-9,66	11,58	1,47
83	71,5	-13,48	12,33		-13,50	10,96	1,68	69,83	-13,62	11,40	1,62 1,92
84		-15,07	12,12		-13,92	8,73	3,59		-14,40		
85		-19,75	15,51		-21,46	16,39	2,07			9,43	2,78
86	36,69	-31,82	23,66	36,32	-36,81	23,26			-21,59	17,19	2,58
87	46,08	-2,07	23,00				5,02		-36,72	24,58	5,03
88				47,04	-1,10	0,13	1,61	46,37	-1,81	0,36	0,75
00	92,14	-4,27	3,62	93,42	-3,80	3,86	1,38	92,36	-3,44	3,99	0,93

ACO 2733US Serial No. 09680089

	Cold	orimetric	data	Siı	multaneo	ous	1	Calibr	ation pre	ecedes	
		asured w			asuring			1	neasurin		
		trophoto			alibratio					9	
Colour	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real	ΔE* _{ab} -	L*-sing	a*-sing	b*-sing	ΔE* _{ab} -
Color							real	•			sing
89	64,1	-9,61	6,11	63,08	-9,95	6,58	1,17	62,78	-10,46	6,86	1,74
90	77,38	-11,04	7,27	76,38	-9,96	6,19	1,83	76,10	-9,60	6,46	2,09
91	84,65	-13,66	8,73	84,28	-13,15	8,43	0,70	84,55	-13,32	8,46	0,44
92	20,03	-13,51	6,95	21,05	-10,84	6,42	2,91	20,82	-11,13	6,60	2,53
93	16,47	-5,88	3,55	17,88	-4,26	3,74	2,15	17,66	-4,44	3,93	1,91
94	80,15	-7,24	3,29	80,35	-6,80	3,18	0,50	80,13	-6,37	3,79	1,01
95	25,92	-26,75	8,14	27,34	-23,30	10,41	4,37	26,58	-23,45	11,21	4,56
96	24,78	-20,28	10,67	26,14	-18,20	11,50	2,62	25,83	-18,15	12,42	2,95
97	19,87	-17,69	1,36	20,96	-13,31	2,93	4,78	20,71	-13,05	3,23	5,07
98	34,47	-1,78	0,06	33,29	-1,45	0,53	1,31	33,10	-1,85	0,77	1,54
99	66,95	-11,78	0,9	67,00	-11,22	0,70	0,59	67,06	-11,41	1,24	0,52
100	84,68	-14,11	0,5	85,61	-13,50	1,06	1,25	85,17	-12,97	1,53	1,61
101	15,57	-8,82	1,1	17,33	-5,54	1,67	3,77	17,38	-5,57	2,50	3,97
102	66,63	-21,42	1,1	65,80	-20,16	-0,44	2,16	65,70	-20,45	0,43	1,51
103	74,69	-24,05	0,99	73,40	-22,97	-0,51	2,26	73,02	-22,85	0,50	2,11
104	50,57	-8,52	-1,31	51,47	-6,93	-1,28	1,83	50,98	-7,34	-0,79	1,35
105	24,96	-21,45	-3,88	25,48	-17,88	-1,52	4,31	24,87	-18,89	-0,99	3,86
106	89,5	-8	-0,03	89,91	-7,90	0,01	0,43	89,04	-7,27	0,00	0,87
107	78,28	-6,99	-1,42	78,87	-6,57	-1,69	0,77	78,20	-6,55	-0,97	0,63
108	76,27	-9,39	-2,48	76,98	-8.66	-1,88	1,18	76,08	-8,35	-1,24	1,63
109	41,82	-33,66	-10,54	41,30	-34,95	-15,13	4,80	40,07	-35,25	-14,15	4,32
110	13,47	-3,55	-0,46	15,67	-2,50	-0,14	2,45	15,25	-2,69	-0,48	1,98
111	85,64	-11,02	-3,87	86,78	-11,24	-3,27	1,30	85,78	-10,67	-3,05	0,90
112	55,62	-16,3	-9,34	56,25	-16,42	-9,66	0,72	55,42	-16,73	-8,92	0,64
113	74,41	-19,23	-10,85	74,67	-19,05	-11,26	0,52	73,42	-18,53	-9,76	1,63
114	44,63	-22,33	-12,21	44,27	-23,85	-15,99	4,09	43,38	-23,86	-15,08	3,48
115	64,98	-25,34	-13,59	64,98	-26,00	-14,58	1,19	63,82	-25,84		1,28
116	35,8	-25,91	-12,3	37,26	-25,02	-13,64	2,17	35,97	-25,34	-13,44	1,29
117	55,08	-30,07	-18,19	54,22	-32,22	-22,17	4,60	53,28	-32,28	-21,52	4,38
118	84,46	-1,29	0,51	85,21	-1,61	0,87	0,89	84,70	-1,62	1,22	0,82
119	84,05	-8,05	-5,37	84,60	-8,71	-5,55	0,88	83,77	-8,19	-5,10	0,42
120	17,55	-9,69	-8,14	18,39	-8,54	-7,96	1,44	17,26	-8,41	-7,75	1,37
121	75,09	-14,85	-13,41	74,99	-15,49	-14,48	1,25	73,82	-14,81	-13,16	1,30
122	46,22	-16,7	-16,15	46,43	-17,10	-18,57	2,46	45,59	-17,31	-17,69	1,77
123	34,65	-22,41	-17,08	37,28	-21,03	-16,94	2,98	36,13	-21,50	-16,92	1,74
124	35,92	-2,36	-3,28	36,05	-2,35	-5,74	2,47	35,22	-2,54	-5,29	2,13
125	33,28	-7,89	-10,48	33,52	-6,94	-12,78	2,50	31,28	-7,47	-13,03	3,27
126	60,78	-2,18	-2,34	62,32	-2,80	-2,12	1,68	61,92	-2,89	-1,74	1,47
127	88,07	-4,84	-4,32	88,82	-5,48	-4,00	1,04	87,95	-5,08	-3,57	0,80
128	77,27	-5,51	-7,67	77,82	-5,57	-7,50	0,58	76,85	-5,35	-6,89	0,90
129	26,12	-7,6	-10,42	23,03	-7,40	-12,16	3,55	22,22	-7,67	-12,14	4,27
130	46,5	-12,86	-19,97	47,01	-13,83	-22,37	2,64	45,41	-14,44	-22,36	3,06
131	34,35		-23,64	36,29		-22,56	2,57	35,46	-14,67	-22,27	2,04
132	13,95	-6,52	-9,95	14,34	-5,43	-10,92	1,51	12,95	-4,52	-10,88	2,42
133	29,14	-9,05	-17,19	29,02	-7,27	-19,85	3,20	27,22	-7,78	-20,49	4,02
134	38,61	-16,21	-32,23	39,68	-17,01	-31,73	1,43				0,88
104	30,01	710,41	-32,23	J9,00	-17,01	-31,/3	1,43	38,18	-16,19	-31,46	U,00

	mea	orimetric asured w trophoto	ith a	me	Simultaneous measuring and calibration			Calibration precedes measuring			
Colour	L*-ref	a*-ref	b*-ref	L*-real		b*-real	ΔE* _{ab} -	L*-sing	a*-sing	b*-sing	ΔE* _{ab}
Color	- 101	" ''	D 101	Liteat	a -icai	D -leai	real	L -sirig	a -sing	D -51119	sing
135	35,55	-2,44	-8,44	35,85	-2,32	-10,06	1,65	34,53	-2,78	-9,99	1,88
136	30,16	-4,21	-17,49	30,07	-2,97	-19,91	2,72	28,56	-4,03	-20,03	3,00
137	28,41	-10,54	-27,45	29,13	-7,90	-28,72	3,02	27,12	-8,05	-29,60	3,53
138	17,22	-4,06	-20,74	16,25	-4,69	-21,22	1,26	13,12	-5,09	-23,93	5,30
139	63,15	0,23	-0,42	64,10	-0,21	-0,36	1,04	63,94	-0,66	0,18	1,33
140	45,11	0,22	-10,33	46,60	1,61	-9,72	2,13	45,52	0,76	-9,37	1,17
141	24,07	-1,35	-28,46	24,11	-0,98	-30,36	1,94	22,17	-1,52	-31,40	3,50
142	18,96	2,37	-24,13	18,40	0,42	-26,24	2,93	16,61	0,15	-27,22	4,47
143	14,08	0,48	-13,51	13,38	-2,65	-16,50	4,38	12,16	-2,60	-17,19	5,17
144	7,52	0,26	-0,42	13,17	-0,51	-0,46	5,70	12,29	0,43	-0,80	4,79
145	72,89	4,49	-16,85	73,42	4,24	-16,65	0,62	72,85	3,80	-16,07	1,04
146	25,46	8,16	-39,29	23,04	8,45	-42,90	4,36	21,25	8,06	-43,78	6,16
147	13,54	0,94	-0,58	15,28	0,05	0,39	2,18	14,44	0,17	-1,20	1,34
148	33,21	19,83	-12,82	31,61	22,05	-13,55	2,83	30,37	21,19	-14,86	3,75
149	44,52	25,98	-6,76	44,01	26,20	-7,24	0,73	42,96	24,19	-8,56	2,98

Table 4

Average and median of ΔE_{ab} of Examples 1-6

	Number of model parameters	Weighing	Calibration beforehand	Simulta- neous calibration	Grey balancing	∆E _{ab} average	ΔE _{ab} median
1	4	Y		Y		2,26	1,67
2	4	Υ	Y			2,23	1,61
3	4	Υ		Y	Υ	2,21	1,60
4	4	Υ	Υ		Υ	2,15	1,56
5	4			Y		2,91	2,15
6	20			Υ		2,32	1,74

10

 $\label{eq:Table 6} \mbox{ Average and median of ΔE_{ab} of Examples 7-12}$

	Number of model parameters	Weighing	Calibration beforehand	Simultaneous calibration	Grey balancing	ΔE _{ab} average	ΔE _{ab} median
نـــــا							
7	4	Υ		Y		2,20	2,04
8	4	Υ	Υ			2,24	2,18

ACO 2733US Serial No. 09680089

9	4	Υ		Y	Υ	2,59	2,40
10	4	Y	Υ		Υ	2,55	2,25
11	4			Υ		3,12	3,22
12	20			Y		4,44	2,72

Table 5
Measuring data of Examples 7 and 8

	Colo	rimetric	data	Sir	nultaneo	ous		Calibr	ation pre	cedes	
	mea	sured w	ith a		asuring				neasurin		
	spect	rophoto	meter		alibratio					3	
Colour	L*-ref	a*-ref	b*-ref	L*-real	a*-real	b*-real	ΔE* _{ab} -	L*-sing	a*-sing	b*-sing	ΔE* _{at} -
Color							real		١		sing
1	34,21	16,65	16,48	34,23	14,77	19,33	1,60	34,23	14,77	19,33	1,60
2	33,18	15,57	23,9	34,04	14,44	24,83	2,03	34,03	14,53	24,77	2,10
3	35,72	17,79	33,24	34,39	14,77	31,50	2,35	34,38	14,77	31,43	2,41
4	32,08	21,48	17,81	31,48	19,18	20,39	1,72	31,61	19,49	20,44	1,67
5	37,03	23,94	32,59	38,29	20,06	33,84	0,31	38,34	20,24	33,99	0,46
6	33,59	33,8	18,02	31,05	29,59	16,98	5,16	30,93	30,41	17,07	4,95
7	33,58	32,06	24,65	33,61	28,99	26,61	1,26	33,76	29,18	27,19	1,08
8	34,29	37,55	33,64	35,96	35,04	36,93	1,62	35,97	35,19	37,25	1,94
9	45,51	17,17	16,13	45,80	15,32	17,25	0,60	45,80	15,44	17,13	0,57
10	50,32	14,45	24,96	51,21	9,16	26,71	2,45	51,40	9,57	26,90	2,31
11	48,99	16,91	36,51	50,31	9,76	38,19	2,75	50,38	9,80	38,15	2,71
12	50,54	25,58	16,78	52,81	22,78	19,78	2,39	52,72	22,71	19,85	2,41
13	52,96	22,31	32,5	54,30	16,16	35,87	2,05	54,36	16,21	36,05	2,16
14	45,62	32,24	17,62	45,13	28,98	18,54	2,46	45,22	29,10	18,45	2,39
15	50,63	34,07	24,3	51,79	28,81	27,34	2,90	51,95	29,53	27,21	2,21
16	51,8	37,11	36,22	53,99	32,45	41,31	2,55	54,22	33,08	41,63	2,96
17	18,88	15,9	9,19	20,03	13,39	9,41	1,28	20,14	13,72	9,38	1,16
18	29,15	20,6	24,53	29,32	17,30	27,26	1,81	29,89	17,61	27,27	1,46
19	18,05	-5,02	-15,56	15,18	-1,07	-16,41	4,63	15,16	-0,97	-16,55	4,53
20	31,51	51,33	31,58	31,74	45,45	29,20	3,13	31,55	46,96	29,31	3,76
21	26,8	24,49	19,3	26,48	23,43	21,15	1,75	26,51	23,84	21,86	2,32
22	44,94	32,01	44,81	48,16	27,24	47,26	1,69	48,35	27,55	47,82	2,05
23	25,5	9,73	17,32	25,86	7,72	15,96	1,60	25,90	7,75	16,07	1,51
24	35,52	26,71	26,01	35,96	23,77	28,12	0,84	35,94	24,31	28,40	1,30
25	43,32	8,31	32,85	42,79	2,20	32,05	1,46	42,87	2,30	31,93	1,38
26	39,47	42,54	30,09	40,36	50,78	39,66	5,41	40,49	51,04	39,63	5,65
27	47,46	20,61	24,89	47,98	16,46	26,79	1,64	47,99	16,64	26,88	1,58
28	67,01	13,65	34,47	68,44	8,92	37,58	2,29	68,36	8,83	37,57	2,20



ACO2733US Serial No. 09/680,089 Examiner Alavi

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<u>Abstract</u>

5

The invention <u>is pertains to a method of determining a colourcolor</u> formula for matching a selected <u>colourcolor</u> measured with an electronic imaging device, <u>such that which method comprises the following steps:</u>

an electronic imaging device is calibrated by measuring the colour signals of at least two calibration colours, the colorimetric data of each of the calibration colours being known; and

at the same time or in a next step the selected colourcolor is measured with the aid of the electronic imaging device; then

using a mathematical model, parameters are calculated for converting the measured colourcolor signals of the calibration colourcolors are converted to the known colorimetric data and then ;

using the mathematical model and the calculated parameters, the

eolourcolor signals of the measured selected eolourcolor are converted to colorimetric data; and next

using a databank, the colourcolor formula is determined of which the colorimetric data that most closely matches the calculated colorimetric data of the measured selected colourcolor.

20

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The invention also comprises a method of determininges a colourcolor formula for matching a selected colourcolor of textured materials such as special effect paints and; to a method of determininges the colourcolor difference of a selected colourcolor measured with an electronic imaging device compared to a standard colourcolor sample; and-

The invention has the advantage that it is possible to make use of inexpensive consumer electronics. The method according to the invention also makes it possible to measures a specific attribute of the colourcolor appearance, the so-called texture.

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